

AutoML Challenge @ PAKDD 2019

Team: ML Intelligence

Mengjiao Bao^{1,2}, Huixue¹, Yihuan Mao¹, Yujing Wang¹
Microsoft Research Asia¹, Beihang University²

Content

- Overview
- Key Challenge
- Pipeline
- Concept Drift
- Auto Part

Overview



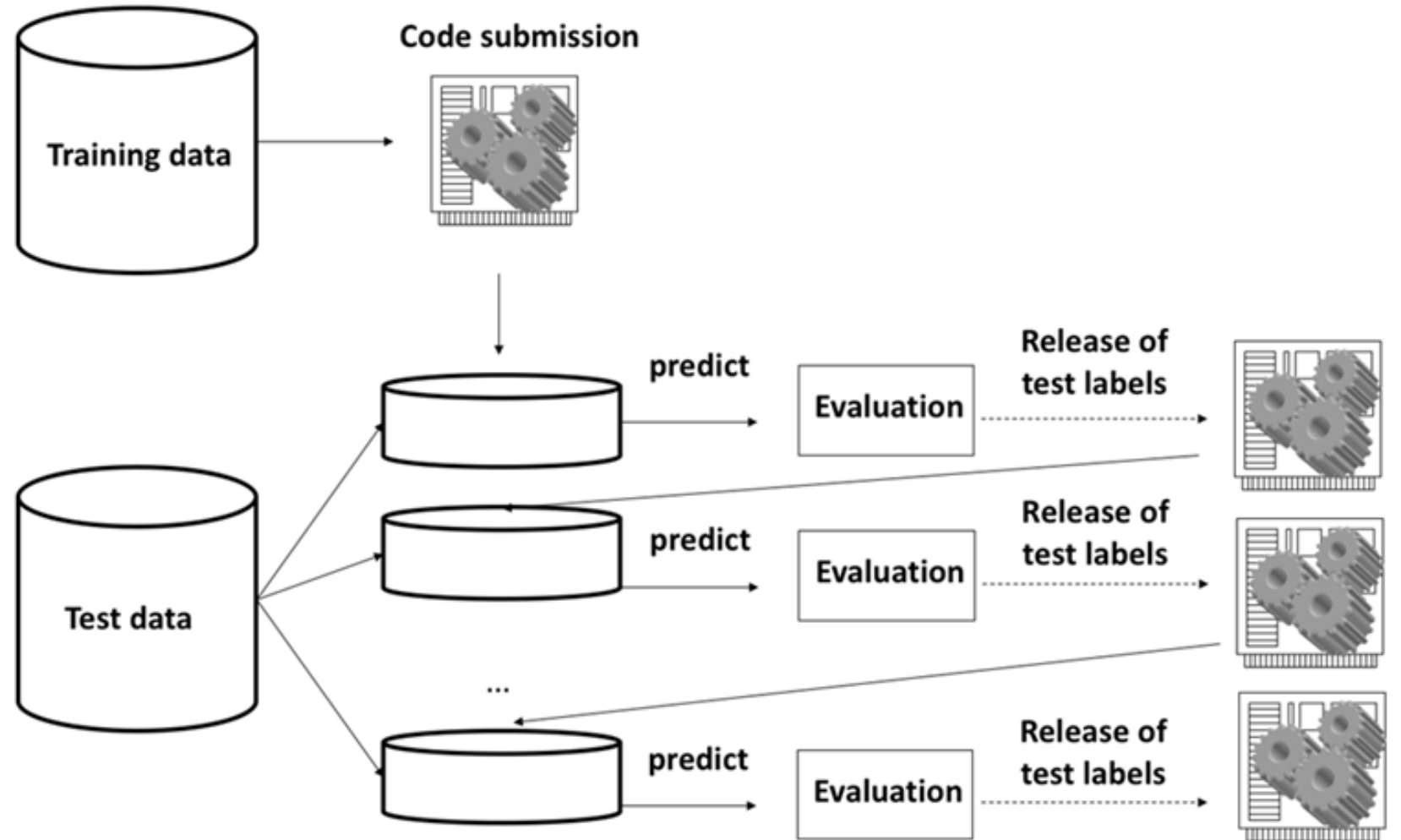
TIME



CAT/MV



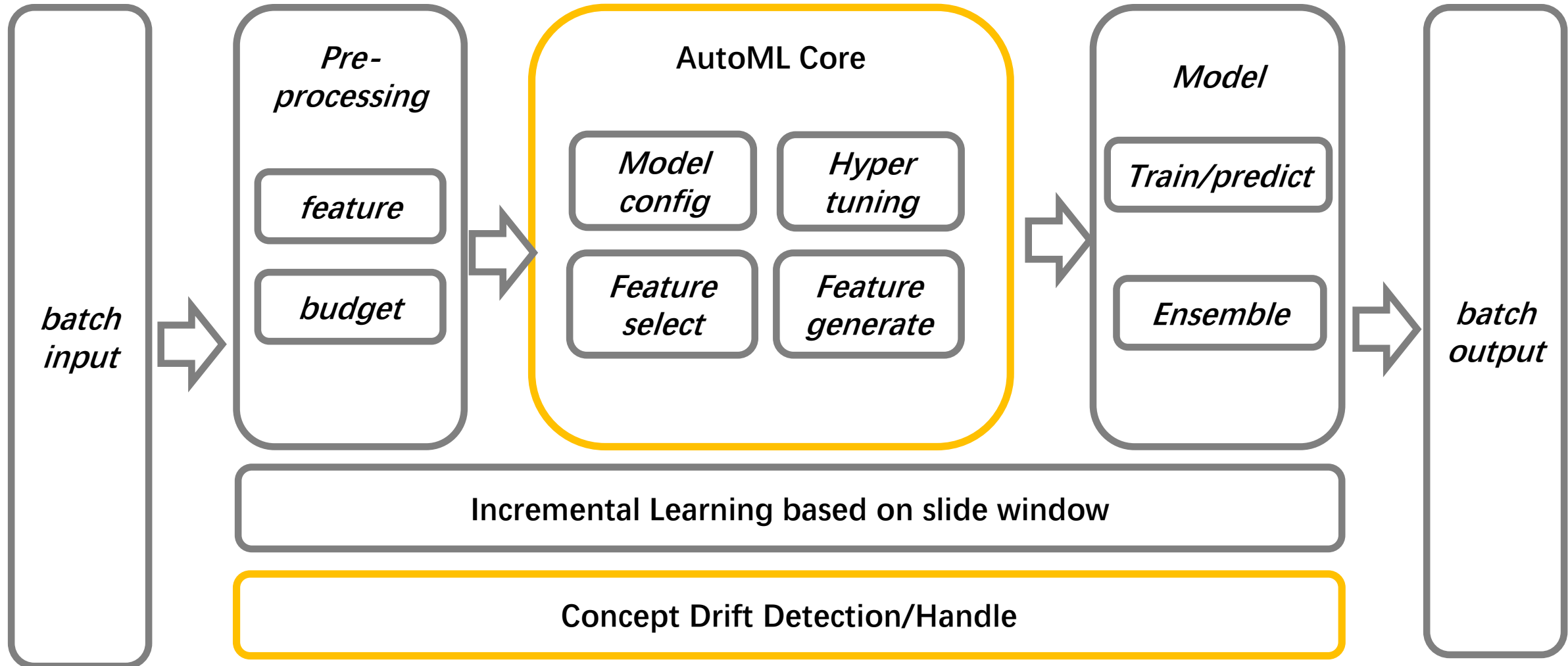
NUM



Difficulties

- **Algorithm scalability:** large datasets(10^7)
- **Varied feature types:** continuous, binary, ordinal, categorical, multi-value categorical, temporal
- **Concept drift:** Distribution change over time
- **Lifelong setting:** Datasets chronologically -> 10 batches, test -> labels reveal.

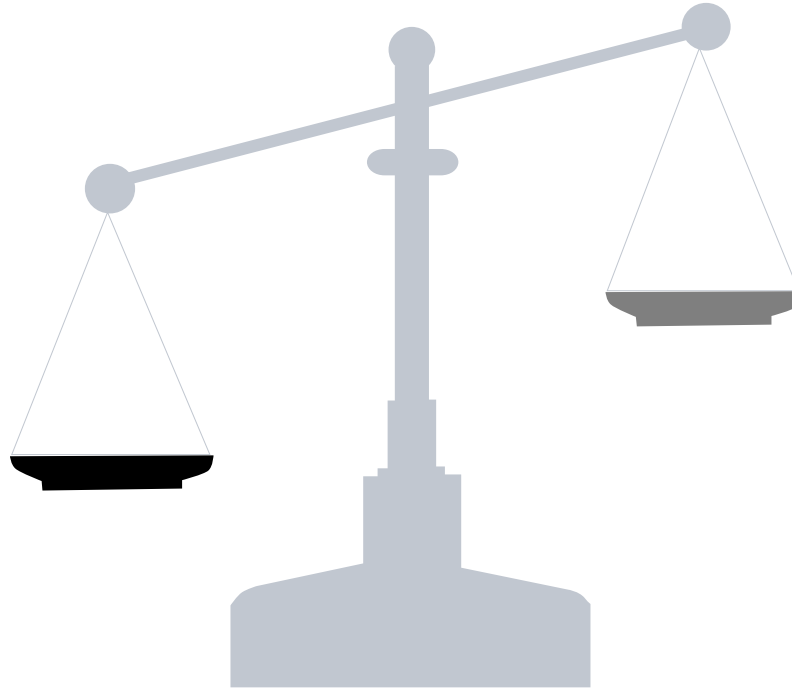
Pipeline



Auto Model Config

Performance

1. More Feature
2. More Data
3. More Parameter



Budget

1. Time Limit
2. RAM Limit

$$Estimate = len(Data) * (\alpha + \beta + \gamma) * len(Cat_{feature})$$

Auto Feature Selection

- Rank methods(for selection and beam search)
 - Naive feature importance generated by LightGBM
 - Bagging methods: 5-kfolds Feature importance average / Bagging with different LightGBM models
 - Feature selection with null importance
- Drop methods
 - time accumulation LightGBM importance

Feature Encoding Methods for HD cat

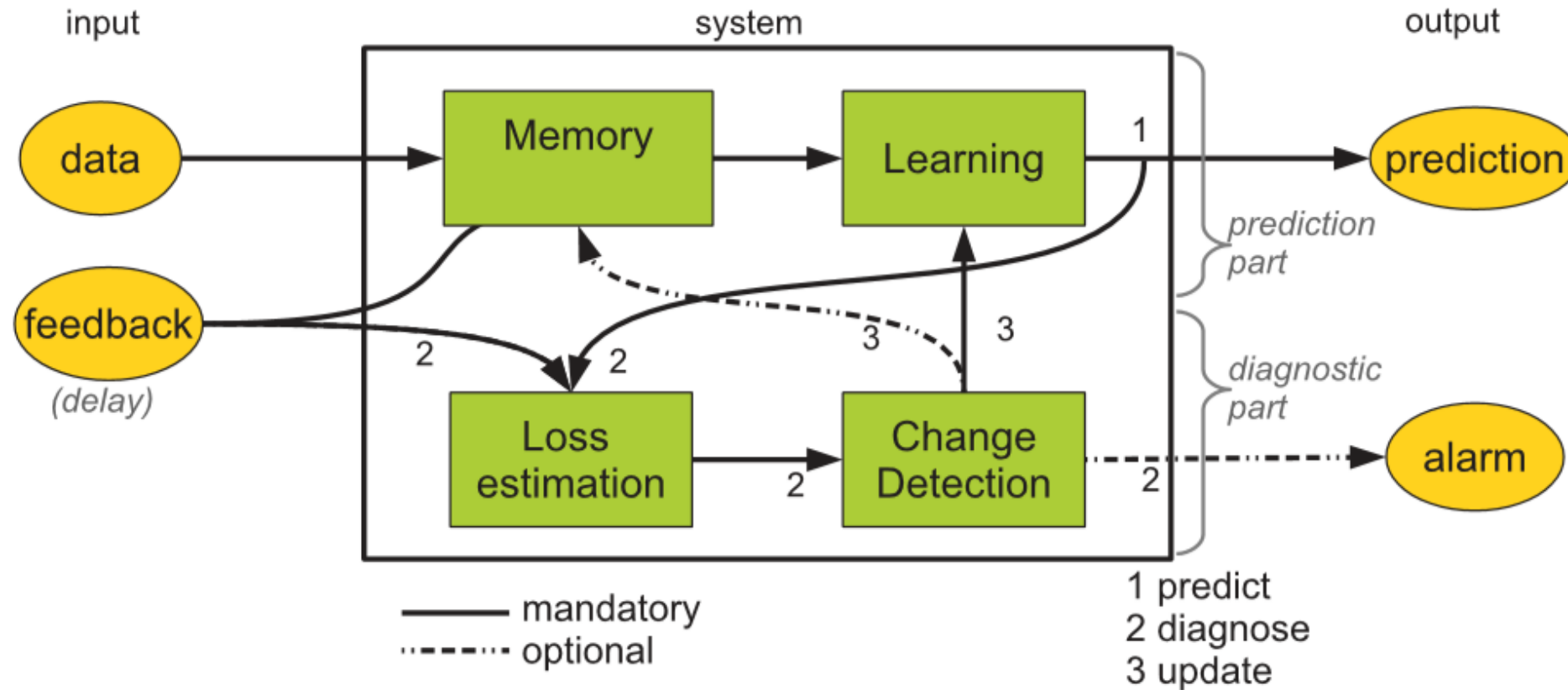
AutoGBT	Hash encode	0.46	0.18	0.45	0.33	0.68
	Incremental encode	0.503	0.278	0.535	0.451	0.732
	Hash + incremental	0.506	0.277	0.505	0.450	0.729
Our method	Hash encode	0.491	0.281	0.480	0.451	0.730
	Count encode	0.513	0.328	0.484	0.569	0.737
	Encode based on first batch	0.533	0.333	0.490	0.571	0.740
	Incremental (slide window)	0.540	0.338	0.555	0.575	0.775

Auto hyper parameter tuning (fix lr)

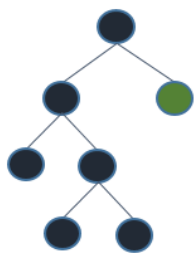
- a. Hyperband
- b. Tree of Parzen Estimators(implements by hyperopt)
- c. metis

	A	B	C	D	E
metis	0.812	0.666	0.848	0.780	0.885
TPE	0.808	0.669	0.884	0.784	0.883
Hand min	0.812	0.661	0.822	0.774	0.885
Had max	0.814	0.672	0.826	0.782	0.886

Handle Concept Drift Overview



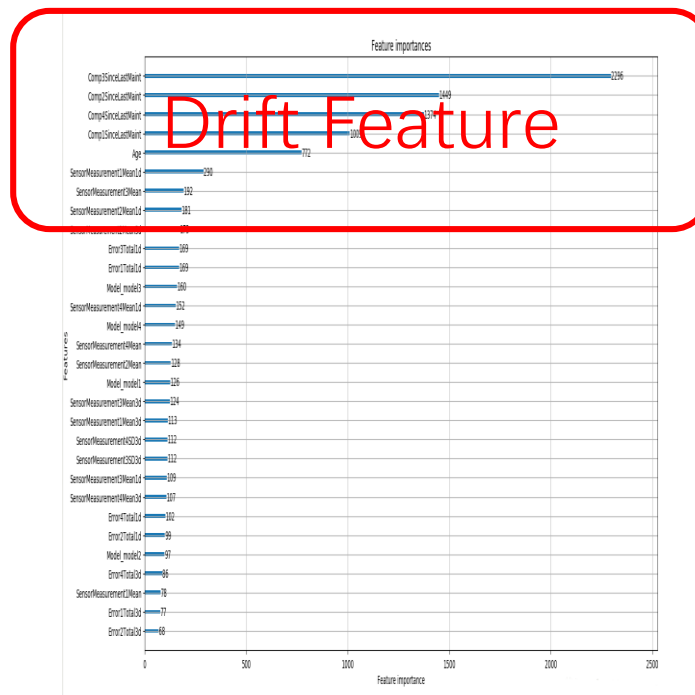
Detection and Handle



TRAIN
POSITIVE

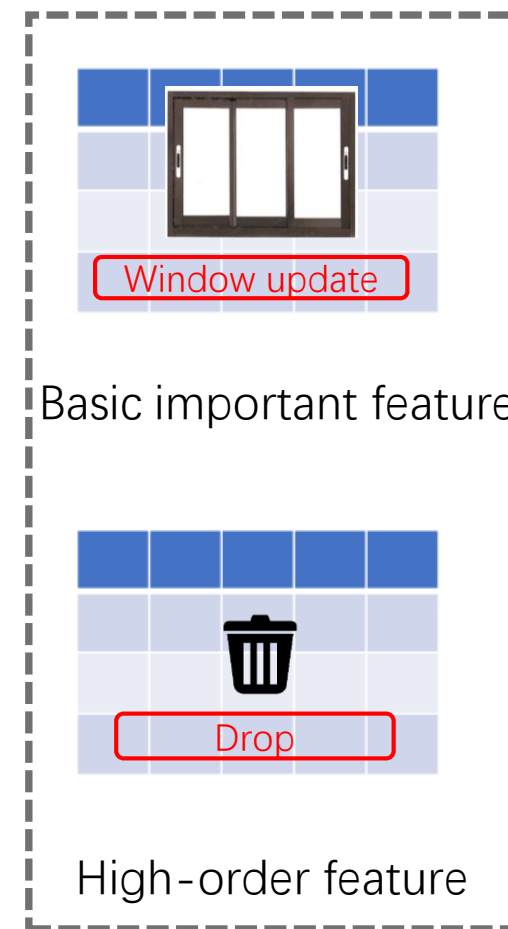
TEST
NEGATIVE

Simple GBDT split train and test



Decision Tree importance

Detection



handle

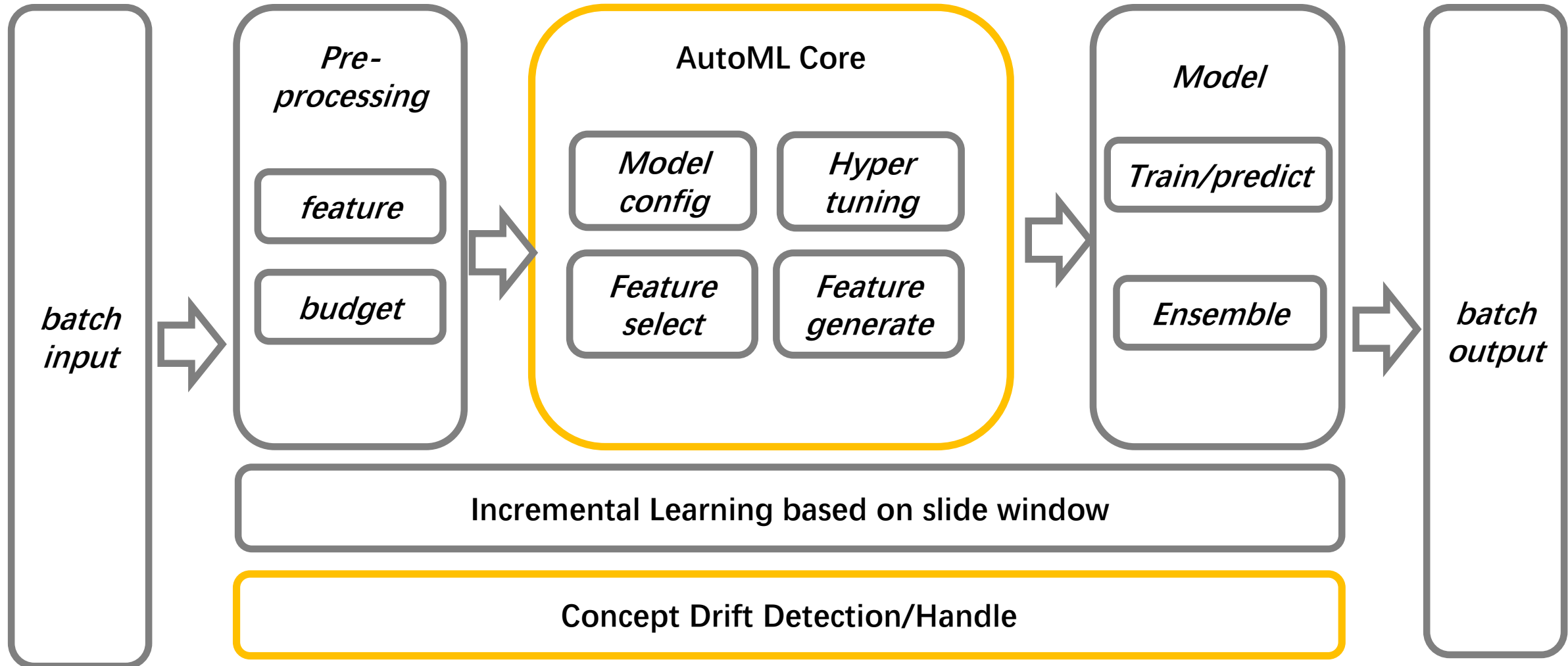
Detection and Handle

Algorithm 2 Concept Detection and Handle

Input: TrainSet D_{train} , TestSet D_{test}

- 1: Set TrainSet D_{train} as positive, TestSet D_{test} as negative;
 - 2: Train a binary classifier by GBDT to split train and test.
 - 3: get the *auc* score in training procedure.
 - 4: Calculate the feature importance and train set *auc* score.
 - 5: if $auc > 0.65$, get the most n largest gain feature as F_{drift} .
 - 6: get concept drift feature set F_{drift}
 - 7: **for** $f \in F_{drift}$: **do**
 - 8: **if** $f \notin F_{highorder}$: **then**
 - 9: delete f from F_{drift} .
 - 10: **end if**
 - 11: **end for**
 - 12:
 - 13: **return** Out put F'_{drift}
-

Conclusion



Q&A



Neural Network Intelligence

<https://github.com/Microsoft/nni>

